Gang Scheduling with Lightweight User-Level Communication

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Motivation

Buffered Coscheduling - a new approach to resource management: Bufferered Coscheduling addresses the following issues:

- Improved utilization of system resources
- Improved responsiveness
- Transparent fault-tolerance (self-healing)

http://www.lanl.gov/~fabrizio

Motivation (cont.)

- First implementation of BCS will use the Quadrics hardware to exploit the advantages of the hardware and software.
- We present a preliminary study of the advantages to scheduling by analysing Quadrics' scheduler, RMS:
 - How does the software and hardware of the Quadrics interconnect affect scheduling?
 - How does the Quadrics scheduler RMS perform?

Outline

- Background: The Quadrics HW and SW
- Experimental goals and methodology
- Experimental results
- Conclusions

Background

The Quadrics Hardware

- Processes can map portions of their address space into the Elan and read/write to other processes address space through the network.
- The Elan network interface card (NIC) has a dedicated processor and 64 MB of SDRAM.
- The NIC has its own TLBs.
- A context switch does not require buffer flushing, only TLB changes in the NIC.
- Capable of delivering more than 300 MB/s of data.

Background (cont.)

Gang Scheduling

- Schedule and deschedule all processes of a job together using global context switch.
- Jobs "believe" they have a dedicated machine.
- More responsive than batch systems.
- Better utilization of resources under varying workloads.
- Can incur overheads: TLBs, communication buffers, swapping.

Background (cont.)

The Quadrics gang scheduler (RMS)

- connects a cluster of computers with a management and Quadrics network.
- Manages cluster resources including PEs and user-level communication.
- Composed of a set of programs, daemons and an SQL database.

Background (cont.)

Example: running a program in RMS



Goals

- 1. Measure overhead of gang scheduler under varying conditions:
 - (a) Memory requirements.
 - (b) Timeslice values.
 - (c) Latency-bound communication.
 - (d) Bandwidth-bound communication.
- 2. Scalability issues:
 - (a) Number of nodes.
 - (b) multiprogramming level.

Experimental Methodology

- We developed a micro-benchmark that performs computation and communication.
- The following parameters are adjustable:
 - Number of computation cycles.
 - Amount of memory used. Large stride is used to avoid cache benefits.
 - Number of total exchanges (TEs) and TE buffer size.
- An external Perl script is used to run predefined sets of experiments.

Experimental platform

- 1-16 dual Pentium-III 733 Mhz nodes.
- 64 MB/s, 66 MHz PCI bus.
- 1 GB ECC SDRAM per node.
- First node serves as management node for pmanager.

Workload



Time

Workload (cont.)

Default parameters for experiments

- Computation amount: 10^8 cycles (equivalent to ≈ 50 CPU seconds).
- Array size of 1 MB.
- Timeslice quantum: 30 sec.
- Number of nodes: 8 (16 PEs).
- 1,024 total exchanges with a buffer size of 4KB (≈ 1 total exchange per 50 ms of computation).

Results - Memory Requirements



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Results - Timeslice Quantum



Slowdown as a function of timeslice (Array size=1MB, buffer size=4KB, 1024 total exchanges, 8 nodes)

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Results - Latency-Bound Communication

Slowdown as a function of total-exchanges (timeslice=10 sec, 8 node, buffer size=1 byte)



Results - Bandwidth-Bound communication



Slowdown as a function of communication buffer size (timeslice=10 sec, 8 nodes, 1024 TEs)

Results - Bandwidth-Bound communication



Slowdown as a function of communication buffer size (timeslice=10 sec, 8 nodes, 1024 TEs)

Results - Multiprogramming level



Slowdown as a function of multiprogramming level (1024 TEs of 4Kb, array size=1MB, 8 nodes)

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Results - Node scalability

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- Scheduler is relatively insensitive to memory requirements (when not swapping).
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- ★ Very sensitive to timeslice quantum.

Resources

More information can be found at

http://www.c3.lanl.gov/~fabrizio

Quadrics web site

http://www.quadrics.com

Or by sending an email to

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