# Parallel Job Scheduling Under Dynamic Workloads

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#### **JSSPP 2003**

Background and methodology

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- Effect of multiprogramming Level
  - What multiprogramming levels should we use?
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- Effect of time quantum on Gang Scheduling
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  - What is the effect of different architectures?

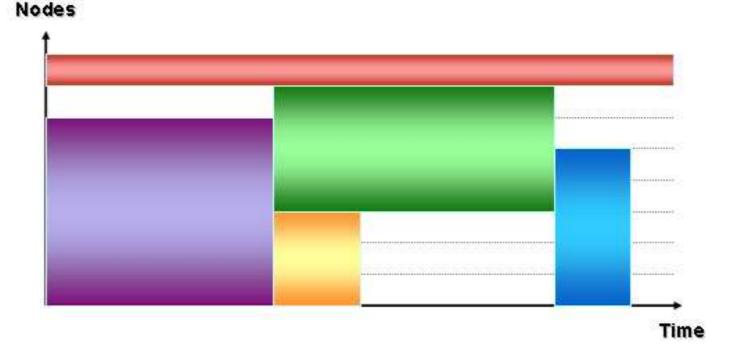
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  - What is the effect of different architectures?
- Effect of load
  - How do different algorithms compare?
  - What type of jobs benefit from different algorithms?

# **Motivation**

- An up-to-date and comparative evaluation of job scheduling algorithms
- Actual implementation on a modern cluster, with communication processes
- Focus on complex, dynamic workload, capturing feedback effects

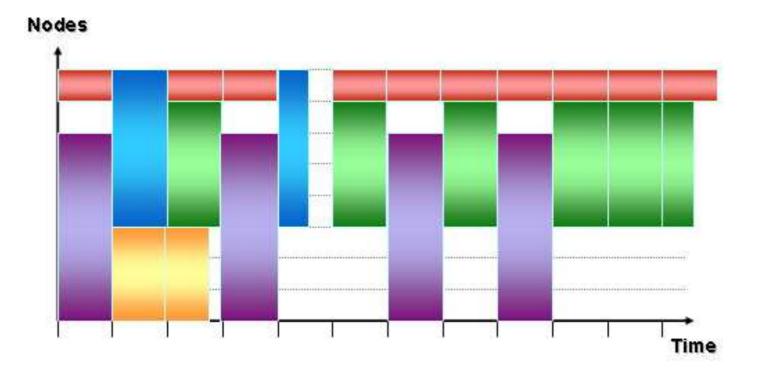
# First-Come-First-Serve (FCFS) Scheduling

- Processors are divided to partitions
- Each job runs to completion in its dedicated partition
- Backfilling techniques for queue management



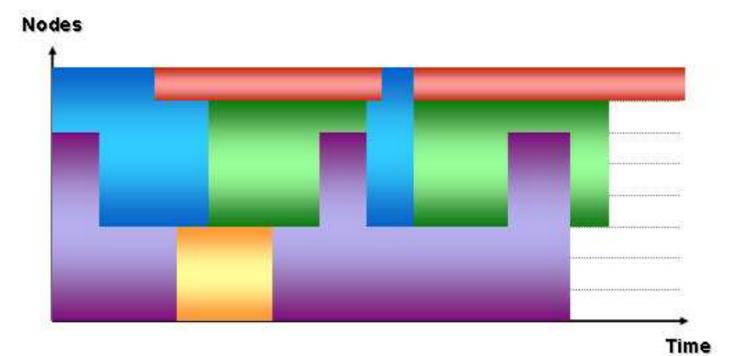
# **Explicit (Gang) Coscheduling**

- Gang Scheduling (GS): coordinated context switching
- Context switch incurs overhead and cache pressure
- Scalability issues with global context switch



# **Implicit Coscheduling**

- Various methods: DCS, SB, PBT, ICS,...
- Use only local information for coordination
- Good for load-imbalance and utilization
- Not ideal for fine-grained jobs

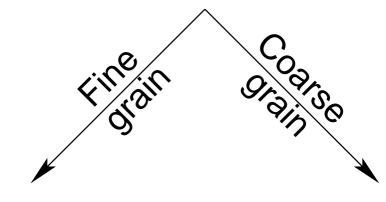


# **Flexible Coscheduling (FCS)**

- Use global coordination with local information
- Monitor processes' communication activity
- Classify processes based on communication
- Schedule processes according to their needs

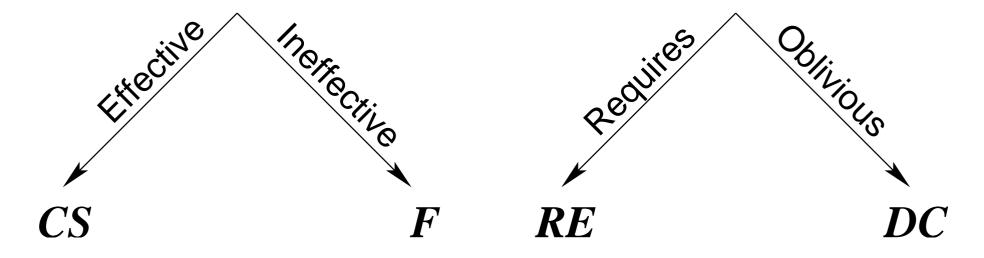
#### **FCS Decision Tree**





#### Coscheduling

Load balancing



# **FCS Scheduling**

Use regular time-slices, but schedule processes based on classification:

- Fine-grained (CS) use explicit coscheduling
- Coarse-grained (DC) use no coordination
  - Local UNIX scheduler
- Load-imbalanced (F) use implicit coscheduling
  - Prioritized Spin-Block

# **Implementation Framework**

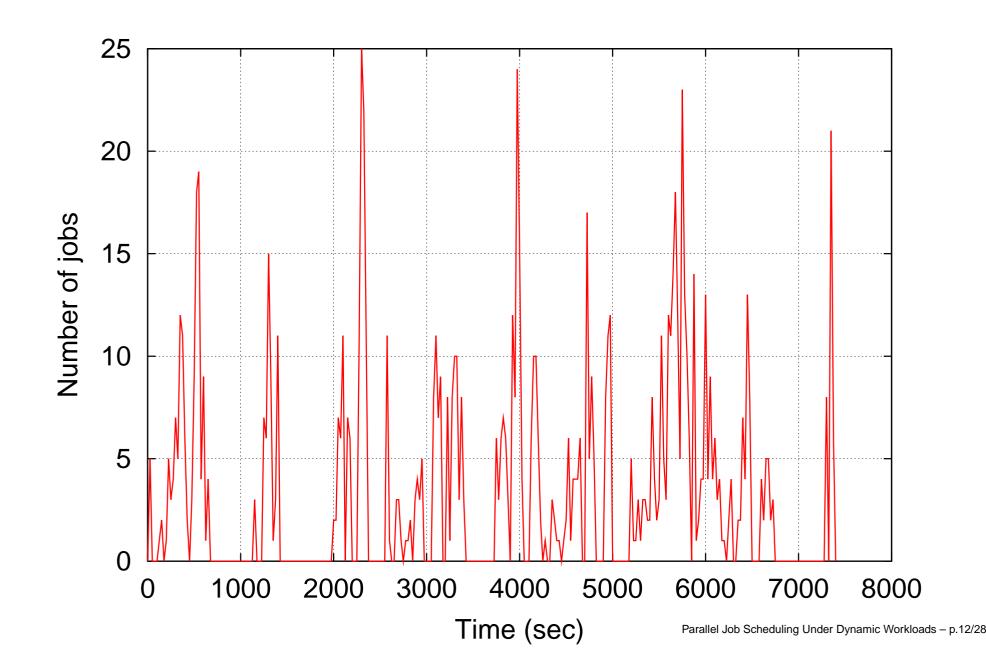
Fully implemented FCFS, GS, SB, FCS using STORM -Scalable Tool for Resource Management:

- Lightweight mechanisms, using HW collective communication primitives
- Scalable to thousands of nodes [SC02]
- "Pluggable" scheduling algorithms (a few more are implemented)
- Ported to x86, IA64 and Alpha architectures, Quadrics interconnect
- Most runs performed on a 16-node 2-way P-III cluster
- Queue management with EASY backfilling (w/all algorithms)

# **Dynamic Workload**

- 1000 jobs with dynamic job arrivals, sizes and runtimes
- Based on detailed model of several traces [Lublin01]
- Synthetic BSP application with different granularities 5ms, 50ms, 50ms
- Multiprogramming levels 1-6
- Timeslices of 50 2000 ms
- Offered load altered by factoring job run-times

# namic Workload Characteristics (75% loa



# **Effect of Multiprogramming Level**

What is a good MPL value?

Tradeoff between overhead and utilization
 Relative effect of backfilling

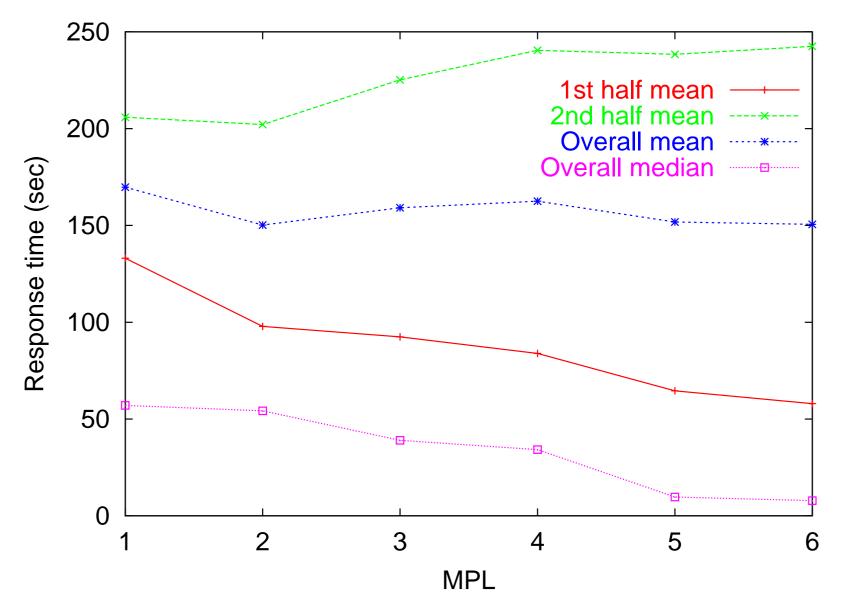
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In most real scenarios, MPL is limited by memory

### **MPL - Response Time**

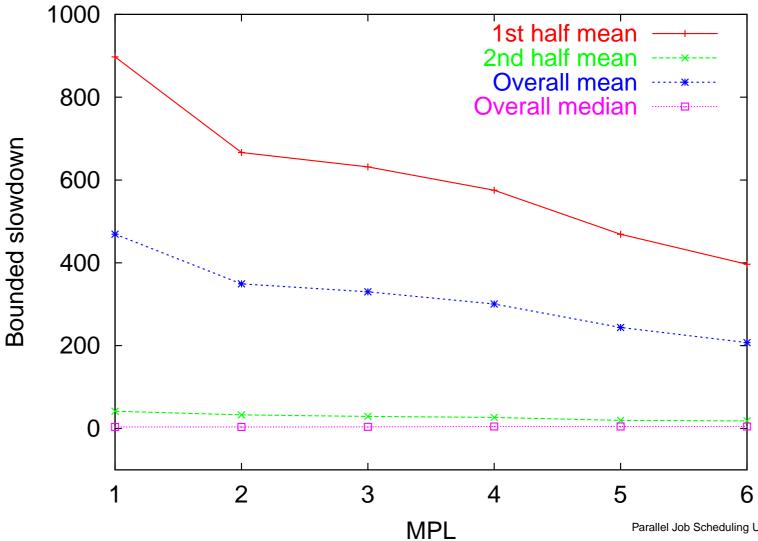


### **MPL - Bounded Slowdown**

Bounded Slowdown = max 
$$\left\{\frac{T_w + T_r}{\max\{T_d, \tau\}}, 1\right\}$$

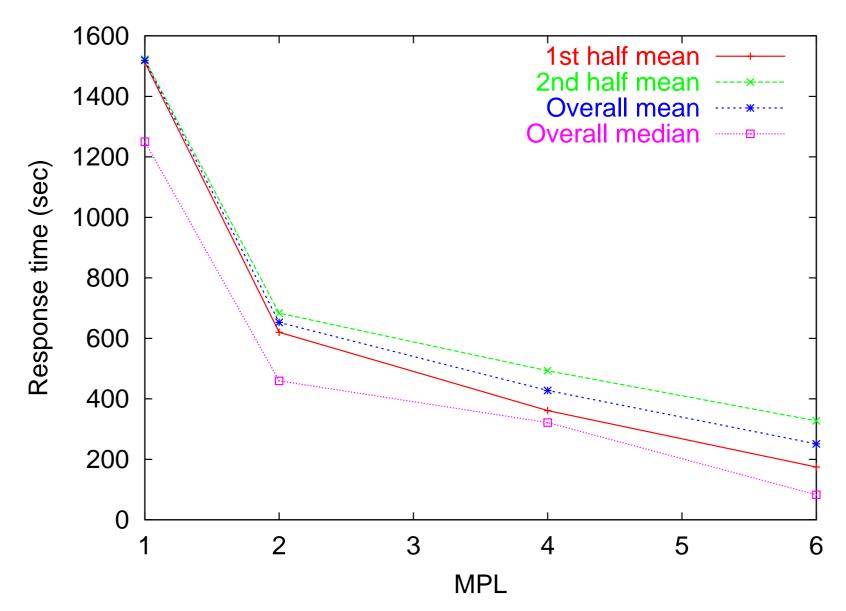
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# MPL - Response Time with no Backfilling



# **Effect of Time Quantum**

What is a good time quantum value?

Tradeoff between overhead and responsiveness
 Some networks allow for some interleaving of communication and computation
 Different architectures have different overheads
 Cache pressure depends on application

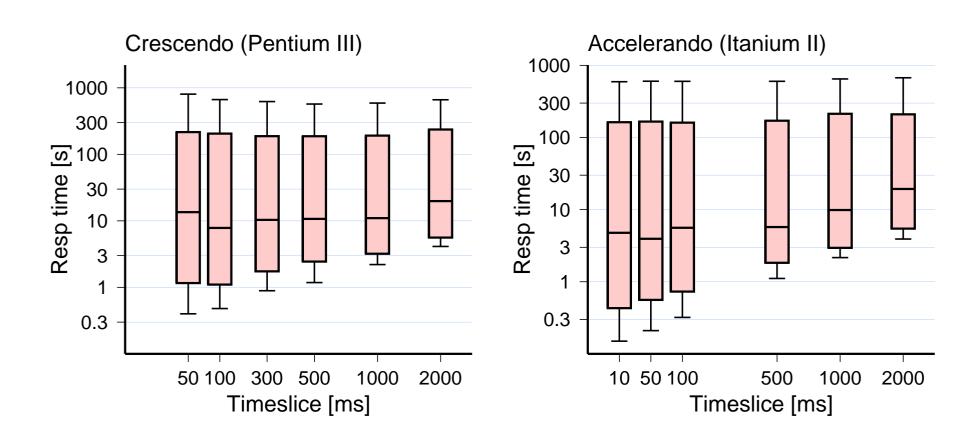
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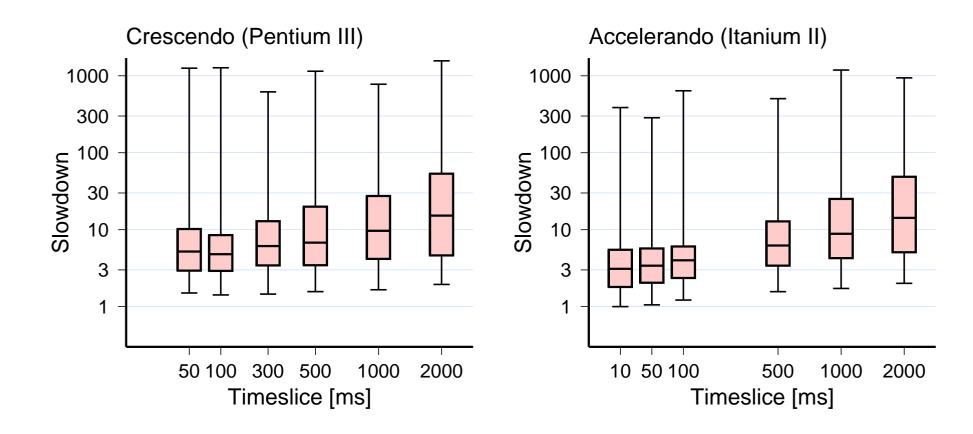
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Lower (sustained time quantum) is better (utilization, responsiveness)

# Time Quantum vs. Response Time



# Time Quantum vs. Slowdown



# **Effect of Offered Load**

What is the effect if increasing load in a dynamic workload?

Different offered load values obtained by factoring run times algorithms compare?
 Comparison of Batch, Gang Scheduling, Two-Phase Spin-Block and Flexible Coscheduling
 Analysis of different types of jobs

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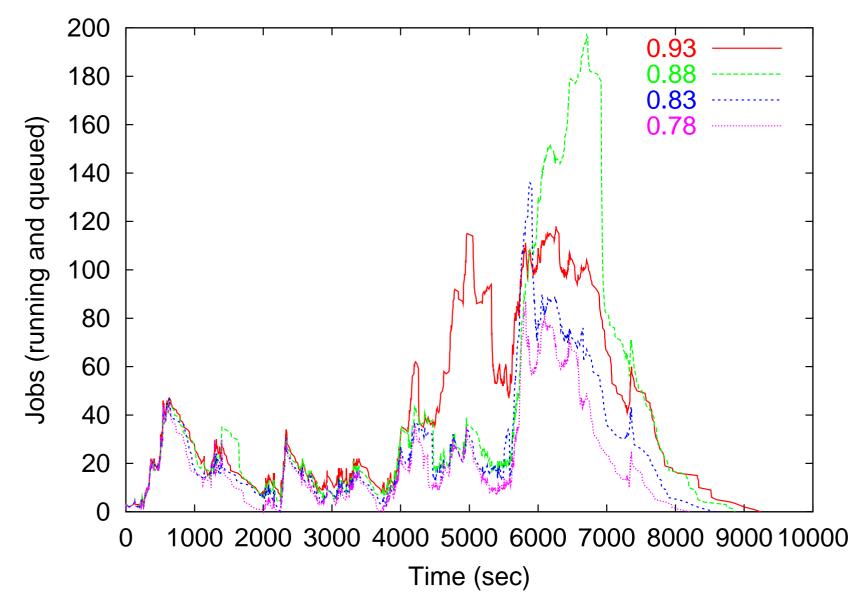
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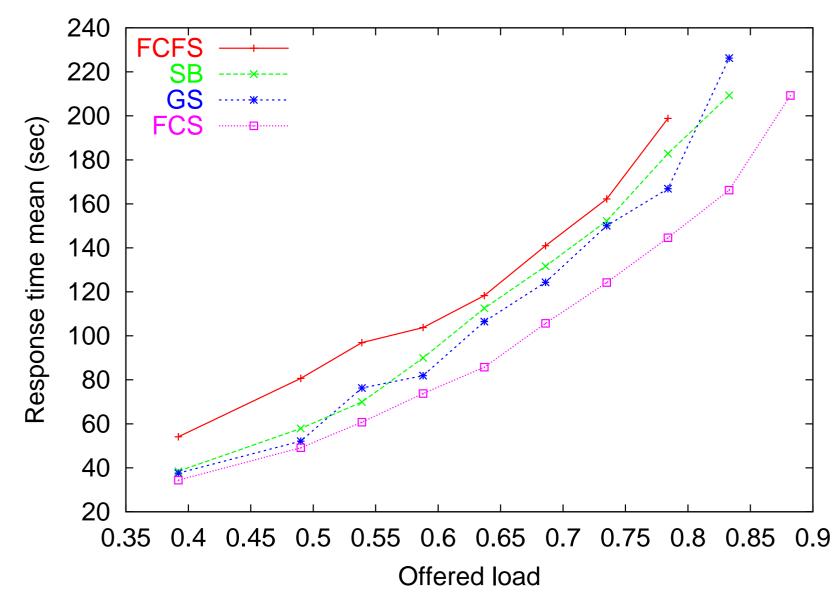
Caveat:

Finite workload hides saturation point

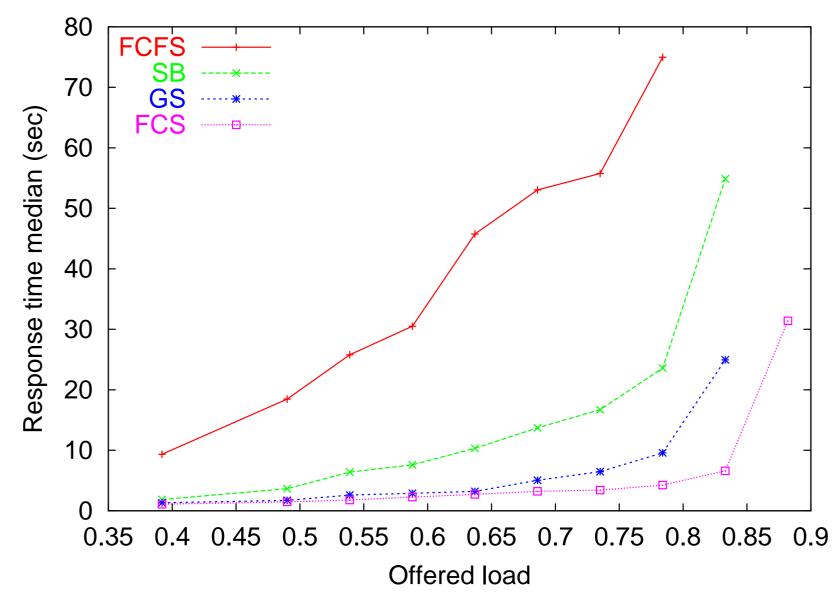
# **Determining Saturation (GS example)**



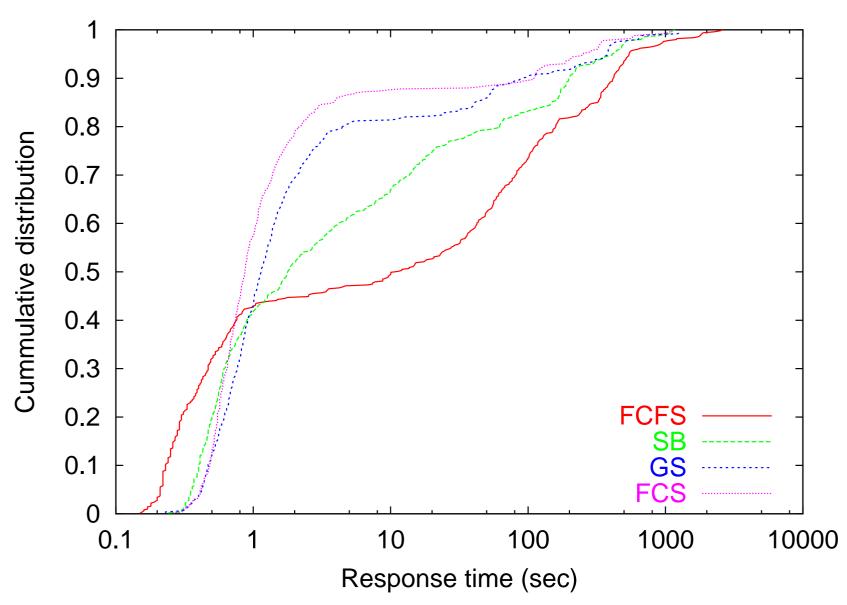
# **Mean Response Time**



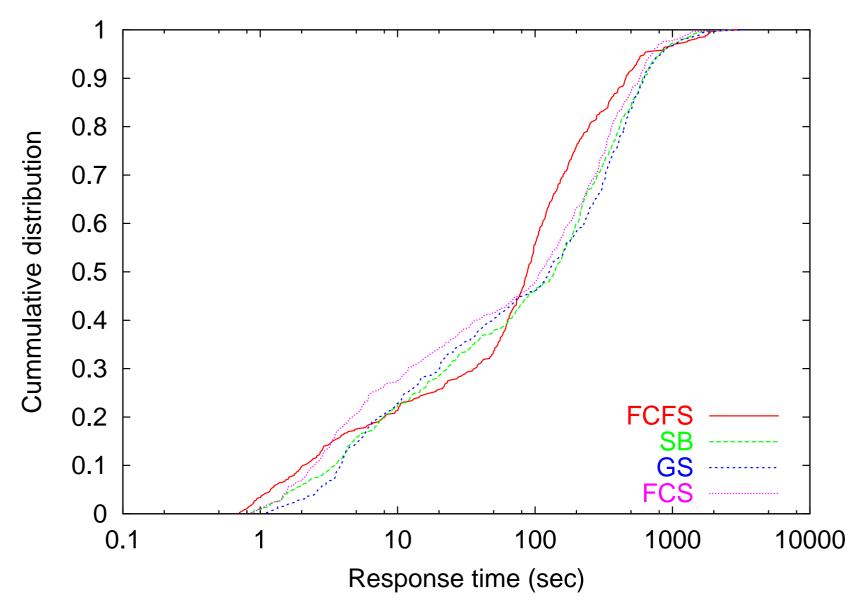
# **Median Response Time**



#### **Short Jobs CDF**



#### **Long Jobs CDF**



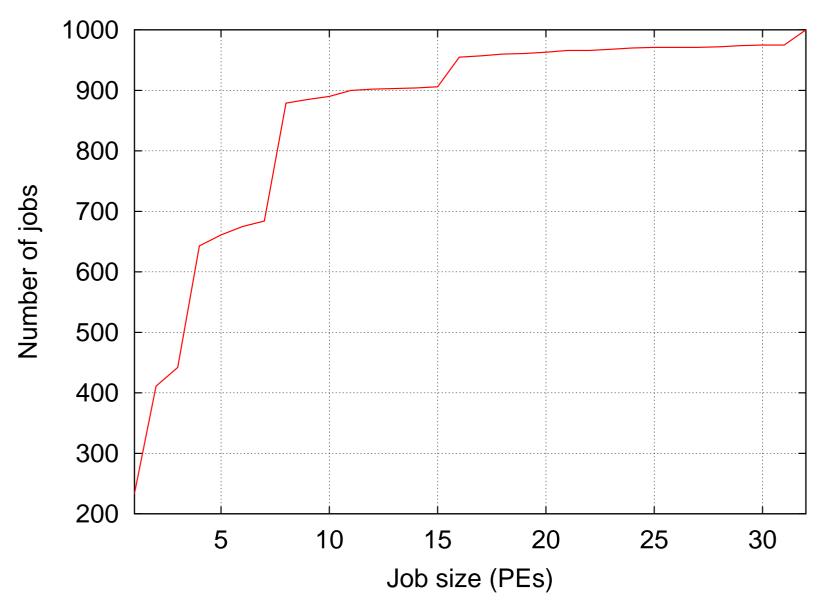
# Conclusions

- Preemptive (coscheduling) techniques improve responsiveness and utilization over non-preemptive scheduling.
- Combining backfilling (knowledge of the future) with preemptive scheduling is indeed effective, even at low multiprogramming levels.
- Not all techniques are equal under dynamic workloads: The more flexible the scheduler, the denser the packing and the better the response time and utilization.

For more information:

http://www.cs.huji.ac.il/~etcs
email: etcs@cs.huji.ac.il

# **Some More Workload Properties...**



# **FCS Phase Diagram**

